

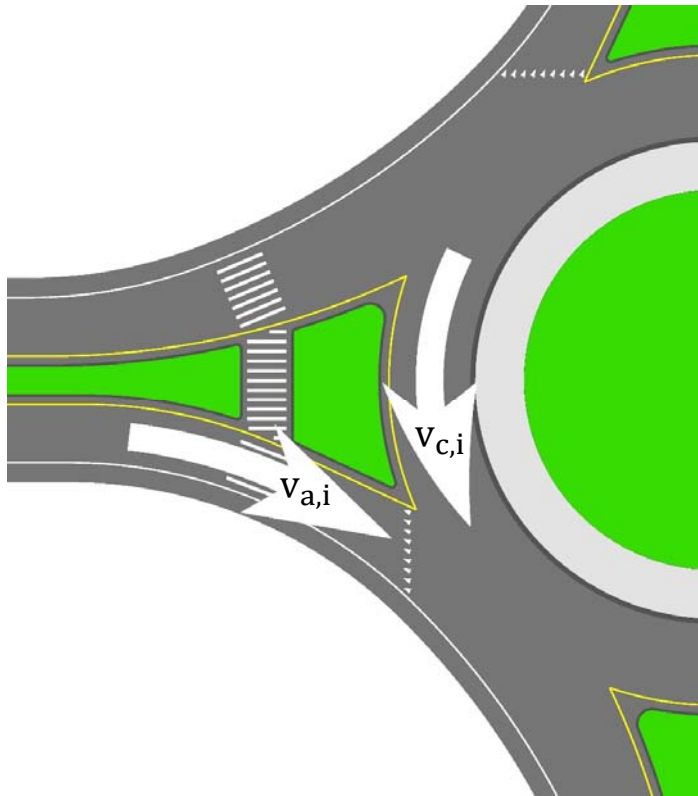


Assessing Robustness of Planning Level Tools for Predicting Roundabout Behavior

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How well does it map?



Critical Sum Analysis

- $CS_i = v_{a,i} + v_{c,i}$
 - $v_{a,i}$ = the demand flowrate on approach i (veh/hr)
 - $v_{c,i}$ = the circulating flowrate passing in front of approach i (veh/hr)

HCM 6th Analysis

- $c_i = 1380 * \exp(-0.00102 * v_{c,i})$
- $d_i = \frac{3600}{c_i} + 900T \left[x_i - 1 + \sqrt{(x_i - 1)^2 + \frac{\left(\frac{3600}{c_i}\right)x_i}{450T}} \right] + 5 * \min[x_i, 1]$
 - d_i = average control delay for approach i (seconds/vehicle)
 - x_i = volume-to-capacity ratio of approach i (unitless)
 - c_i = capacity of approach i (vehicles/hour)
 - T = analysis time period (hour)

How can we say a method is robust?

Primary questions:

1. Is there a well defined relationship (correlation) between critical sum and delay?
2. Among all of the volume scenarios that result in a certain critical sum, do they also result in the same delay?
3. Are there aspects of the volume scenario that impact how closely critical sum predicts delay?



Experiment Design to Assess Robustness

Origin-Destination
Volume
Combination

- Volume by approach (100-2000)
- Split Percentage (0.5–0.7)
- Turn Percentage (0.05-0.25)

Algorithmic
Formulation

- CS_{MAX} (max value of all approaches)
- $CS_{weighted}$ (weighted average)

Model Fit

- Mean correlated value
- Percent of values within ± 5 sec of the predicted mean



Volume Scenario Permutations and Perturbations

| Direction | Parameter | Units | Min | Max | Step | Values | Randomization |
|-----------|--------------------------|-------|------|-------|------|--------|----------------------------------|
| EW | 2 Way Volume | pceph | 100 | 2,000 | 100 | 20 | $-50+[100*\text{Rand}(0,1)]$ |
| | Split percent | % | 0.5 | 0.7 | 0.05 | 5 | $-0.025+[0.05*\text{Rand}(0,1)]$ |
| | Turn percent | % | 0.05 | 0.25 | 0.05 | 5 | $-0.025+[0.05*\text{Rand}(0,1)]$ |
| NS | 2 Way Volume | pceph | 100 | 2,000 | 100 | 20 | $-50+[100*\text{Rand}(0,1)]$ |
| | Split percent | % | 0.5 | 0.7 | 0.05 | 5 | $-0.025+[0.05*\text{Rand}(0,1)]$ |
| | Turn percent | % | 0.05 | 0.25 | 0.05 | 5 | $-0.025+[0.05*\text{Rand}(0,1)]$ |
| Total | 250,000 volume scenarios | | | | | | |

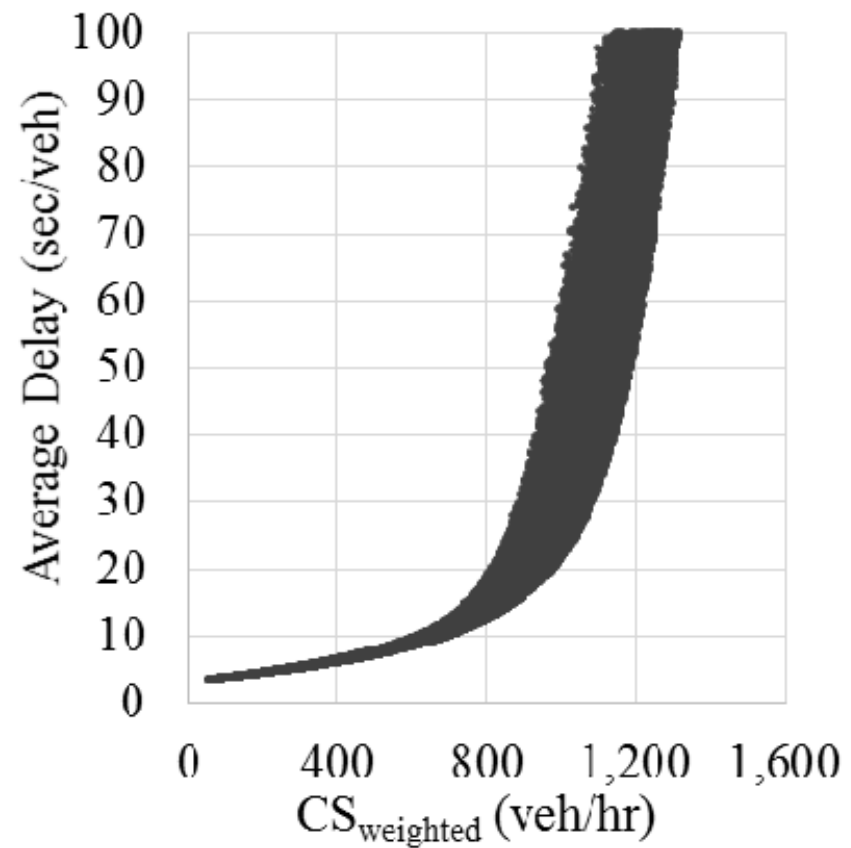
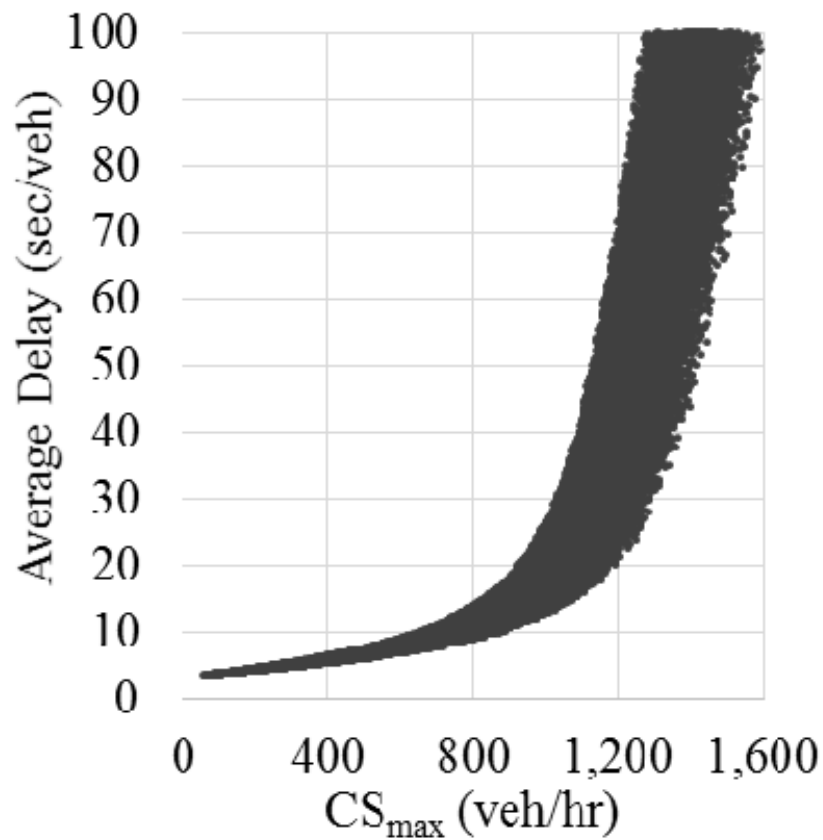


Sample Volume Scenario Application

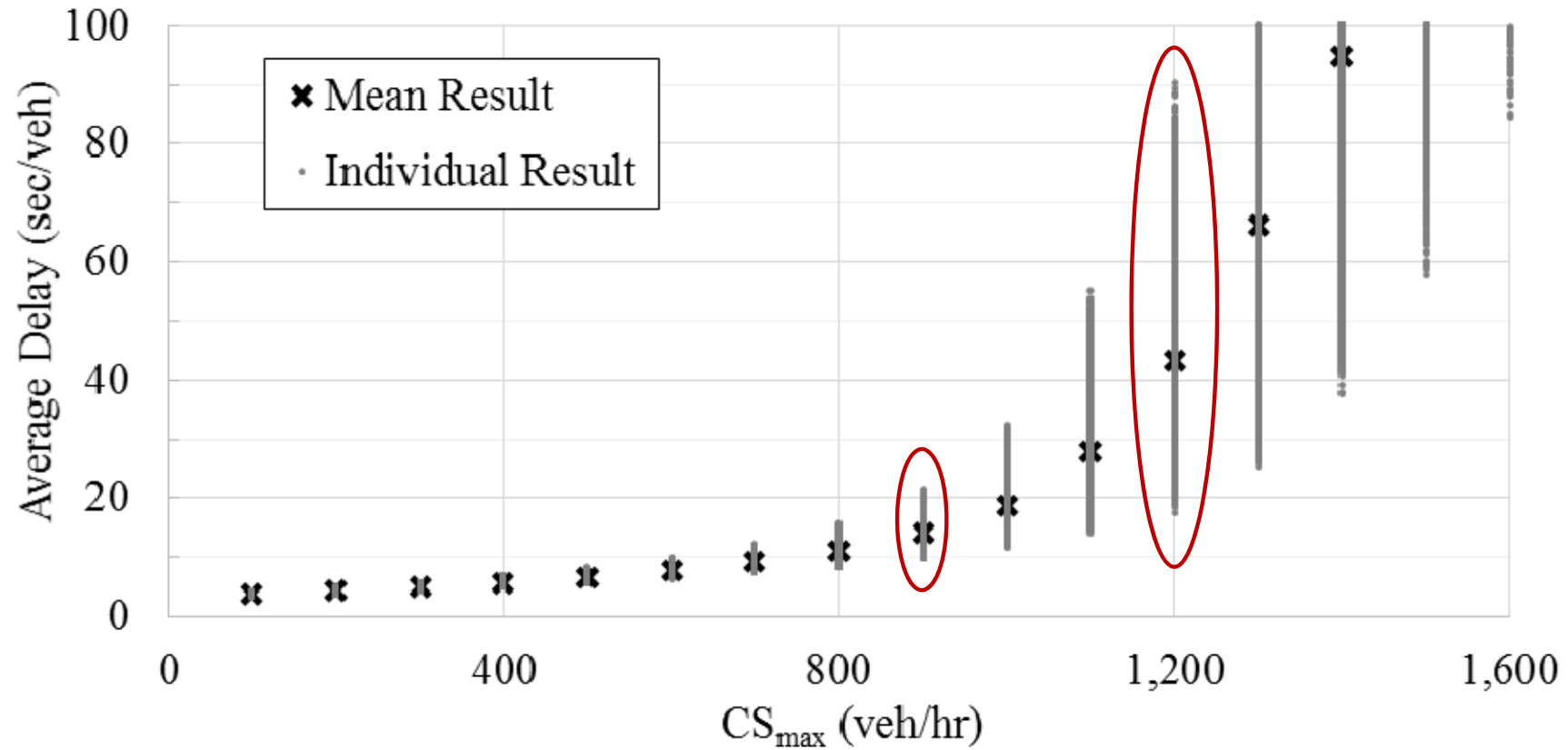
| Input Parameters | | T = 60 min | | | Volume Application | | | | | Critical Sum Method | | | HCM 6th Method | | | |
|------------------|----|------------|-----------|--------|--------------------|----|-----|----|----------|---------------------|----------|-------------|----------------|-----------|-----------|------------|
| Approach | | road vol | dir split | turn % | app vol | L | T | R | circ vol | CS | CS (max) | CS (weight) | cap. | v/c ratio | app delay | int. delay |
| 1 | EB | 800 | 0.6 | 0.1 | 480 | 48 | 384 | 48 | 359 | 839 | 839 | 758 | 957 | 0.50 | 10.0 | 8.58 |
| 3 | WB | | | | 320 | 32 | 256 | 32 | 316 | 636 | | | 1000 | 0.32 | 6.9 | |
| 2 | SB | 700 | 0.55 | 0.15 | 385 | 58 | 269 | 58 | 335 | 720 | | | 981 | 0.39 | 8.0 | |
| 4 | NB | | | | 315 | 47 | 221 | 47 | 490 | 805 | | | 837 | 0.38 | 8.8 | |



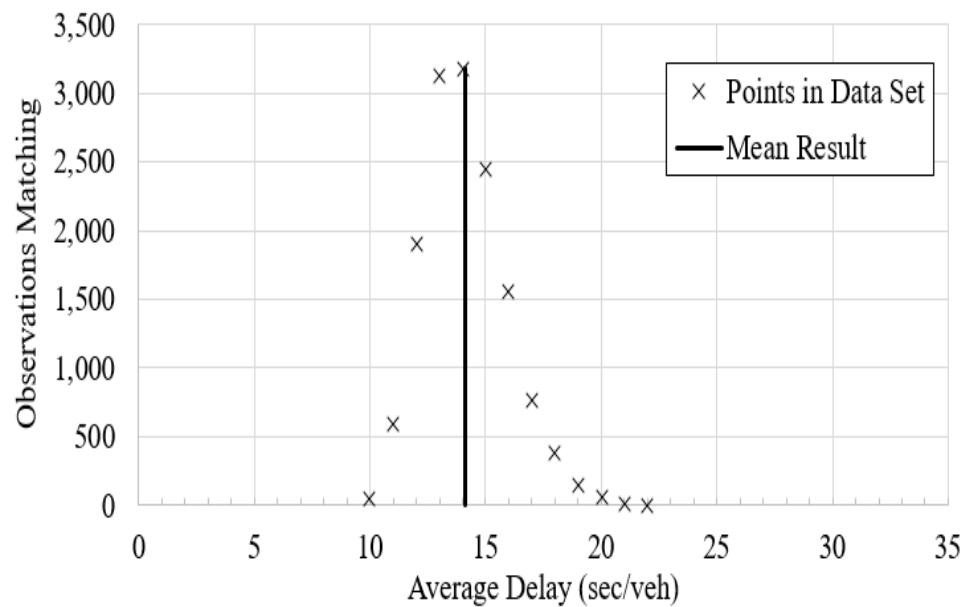
Impact of Max or Weighted Critical Sum Values



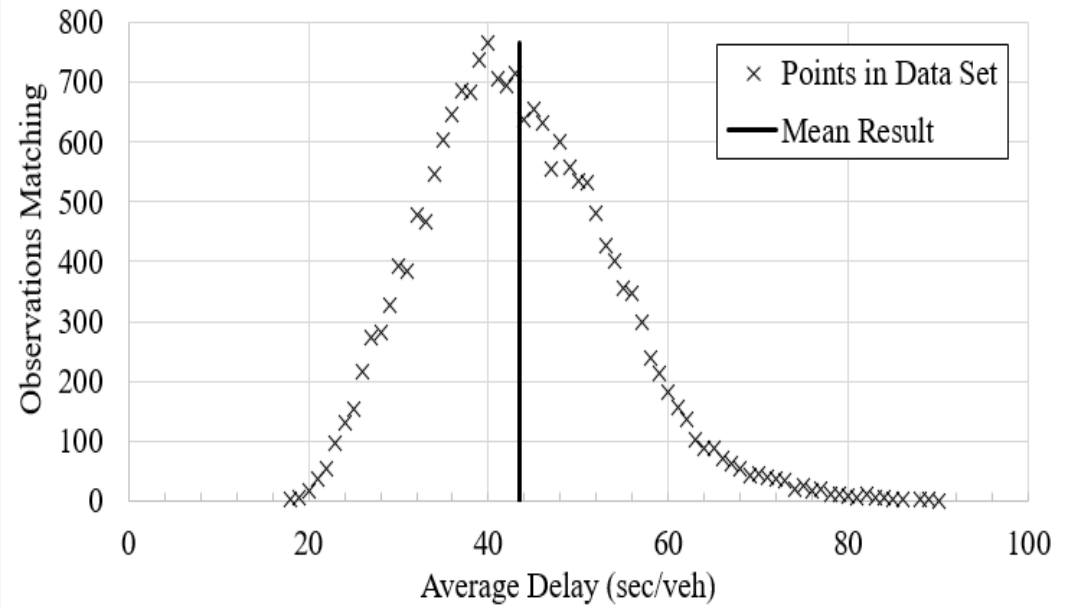
Assessing Reliability of Results



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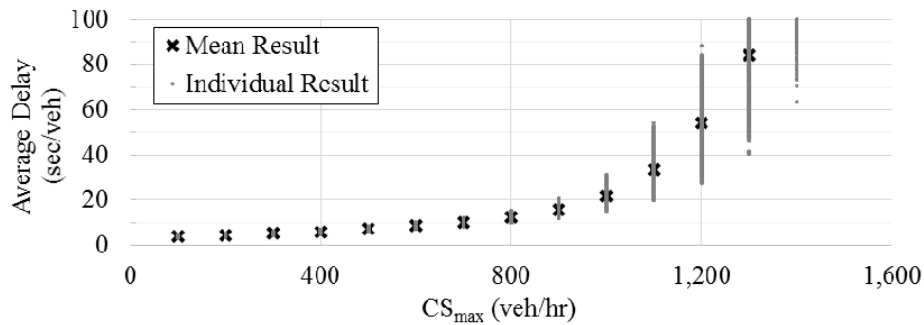
$$CS_{MAX} = 900 \pm 50$$



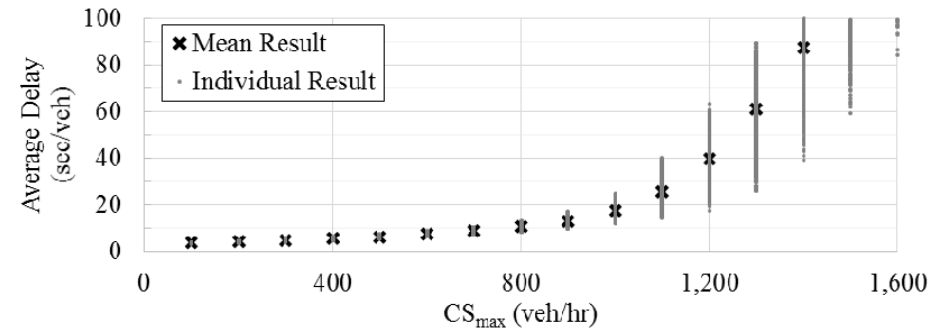
$$CS_{MAX} = 1,200 \pm 50$$



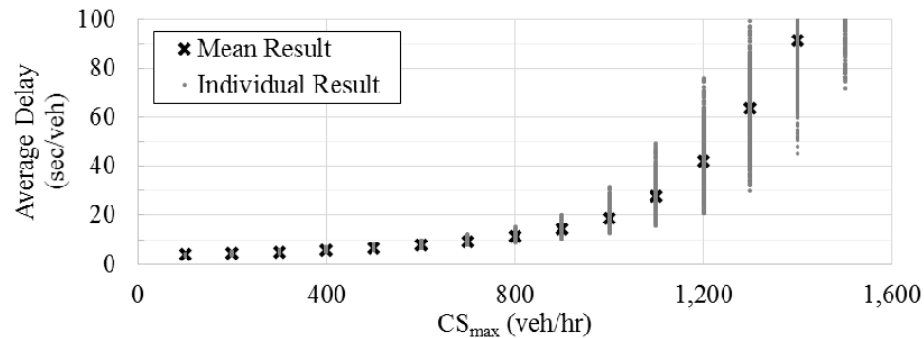
Impact of Volume Scenario Parameters



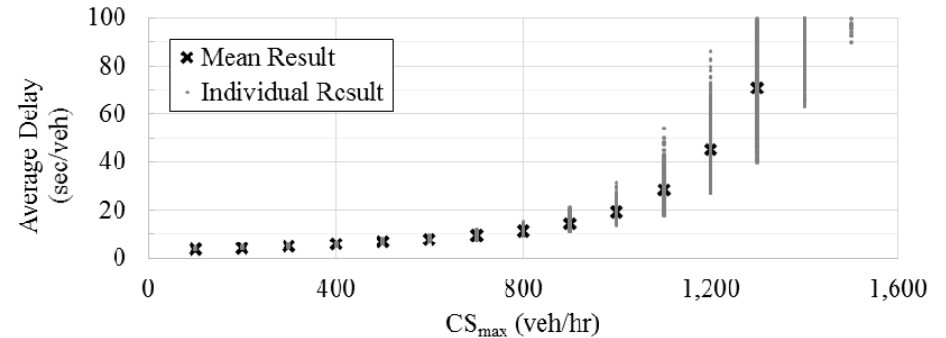
Directional Split: NB/SB = EB/WB = 0.5



Directional Split: NB/SB = EB/WB = 0.7



Turn Percentage: NB,SB,EB,WB = 5% (min)



Turn Percentage: NB,SB,EB,WB = 25% (max)



Conclusion

- Regardless of the volume scenario conditions...
 - Critical sum fails to be an accurate indicator of average roundabout delays greater than 15 seconds.



Paper : Assessing Robustness of Planning Level Tools for Predicting Roundabout Behavior

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